



Francesca Berti¹, Dario Allegretti¹, Alessandro Bertini¹, Giancarlo Pennati¹, Francesco Migliavacca¹ and Lorenza Petrinì²

¹LaBS, Chemistry, Materials and Chemical Engineering Department, Politecnico di Milano

²Department of Civil and Environmental Engineering, Politecnico di Milano

INTRODUCTION

Cardiovascular & peripheral diseases

Clinical treatment with Nitinol stent and percutaneous valves^[1]

Biomedical devices working conditions

The loading cycles are responsible of functional fatigue

Cyclic loads are responsible for the progressive weakening of the material and its subsequent failure

Open issue

Pre-operative crimping: to fit the dimension of the deployment catheter^[2]

Excessive deformations during crimping may lead to yielding

Altered mechanical response due to inelastic strains

A proper constitutive model is needed for a reliable estimation of the device fatigue performance

MATERIALS AND METHODS

Material model formulation

External variables: T, ϵ Internal variables: $\xi = e^{tr} - e^{fix} - be^{pl}$

The thermodynamic potential

$$\Psi = \frac{1}{2} K \theta^2 + G \|e - e^{tr} - e^{pl}\|^2 - 3\alpha K \theta (T - T_0) + \Psi_{tr} + \tau'_M \|\xi\|$$

Elastic energy, Thermal energy, Transformation strain energy, Chemical energy

$$\Psi_{tr} = \begin{cases} \frac{1}{2} \{h_1 + [h'(\omega(t) + \eta(t))]\|\xi\|\}^2, & \|\xi\| \leq \epsilon_L(t) \\ \frac{1}{2} h_2 (\|\xi\| - \epsilon_L(t))^2 + \{h'(\omega(t) + \eta(t))\}\epsilon_L(t)\|\xi\|, & \|\xi\| > \epsilon_L(t) \end{cases}$$

h_1 and h_2 control the slopes during transformation phase

h' controls the slope modification of the transformation plateau due to evolution of fatigue and plastic effects through ω and η

$$\omega(t) = \int_0^t \|\dot{e}^{fix}\| dt$$

$$\eta(t) = \int_0^t \|\dot{e}^{pl}\| dt$$

$\tau'_M = \beta(T - M_f)$ controls the material response at different temperatures

A, Φ and B control the lowering of the loading - unloading transformation plateaus due to fatigue accumulation

FEA of a Transcatheter Aortic Valve Implantation (TAVI)

- The new constitutive model was implemented as an UMAT for User Defined Materials in Abaqus
- The stent frame of a TAVI device was modelled in ABAQUS 6.14-5
- The simulation of a durability test was reproduced twice to account for plasticity and fatigue or not^[3]:

- Step 1: pressurization of the silicone compartment at 100 mmHg
- Step 2: crimping and deployment of the valve
- Step 3: cyclic pressure loads to mimic the in-vivo boundary conditions

RESULTS

Material model Comparison with experimental data

Comparison with the existing model implemented in Abaqus

UMAT

ABQ_SUPER_ELASTIC

Finite Element TAVI simulation

Fully expanded configuration, End of crimping

Most stressed element

Plasticity activated, Plasticity deactivated

181 σ [MPa] <math>< 352</math>
-0.0570 ϵ [-] <math>< -0.0532</math>

-246 σ [MPa] <math>< -95</math>
-0.0233 ϵ [-] <math>< -0.0199</math>

✓ Compressive vs tensile stress
✓ Doubled strain in the plasticity activated model

CONCLUSIONS

Devices are in-vivo subjected to a complex state of stress and in particular to cyclic loadings and post-yielding stress and strain

✓ A new constitutive model for shape memory alloys with plasticity, structural fatigue and their interaction was implemented and validated: it could be a useful tool for studying the device response under in-vivo BCs

➤ Next step: Validation of device behavior prediction